

**10.20 Theorem** Let a function  $G(\omega, \theta)$  satisfy the conditions of **9.31**. Then

$$E\left(\frac{dG}{d\theta}\bigg|_{\theta=\theta_0}\bigg|\mathcal{G}\right) = \frac{dE(G|\mathcal{G})}{d\theta}\bigg|_{\theta=\theta_0}, \text{ a.s.} \quad (10.49)$$

**Proof** Take a countable sequence  $\{h_v, v \in \mathbb{N}\}$  with  $h_v \rightarrow 0$  as  $v \rightarrow \infty$ . By linearity of the conditional expectation,

$$E\left(\frac{G(\theta_0 + h_v) - G(\theta_0)}{h_v}\bigg|\mathcal{G}\right) = \frac{E(G(\theta_0 + h_v)|\mathcal{G}) - E(G(\theta_0)|\mathcal{G})}{h_v} \text{ a.s.} \quad (10.50)$$

If  $C_v \in \mathcal{G}$  is the set on which the equality in (10.50) holds, with  $P(C_v) = 1$ , the two sequences agree in the limit on the set  $\bigcap_v C_v$ , and  $P(\bigcap_v C_v) = 1$  by **3.6**. The left-hand side of (10.50) converges a.s. to the left-hand side of (10.49) by assumption, applying the conditional version of the dominated convergence theorem. Since whenever it exists the a.s. limit of the right-hand side of (10.50) is the right-hand side of (10.49) by definition, the theorem follows. ■

## 10.5 Relationships between Subfields

$\mathcal{G}_1 \subseteq \mathcal{F}$  and  $\mathcal{G}_2 \subseteq \mathcal{F}$  are *independent* subfields if, for every pair of events  $G_1 \in \mathcal{G}_1$  and  $G_2 \in \mathcal{G}_2$ ,

$$P(G_1 \cap G_2) = P(G_1)P(G_2). \quad (10.51)$$

Note that if  $Y$  is measurable on  $\mathcal{G}_1$  it is also measurable on any collection containing  $\mathcal{G}_1$ , and on  $\mathcal{F}$  in particular. Theorems **10.10** and **10.11** cover cases where  $Y$  as well as  $X$  is measurable on a subfield.

**10.21 Theorem** Random variables  $X$  and  $Y$  are independent iff  $\sigma(X)$  and  $\sigma(Y)$  are independent.

**Proof** Under the inverse mapping in (10.13),  $G_1 \in \sigma(X)$  if and only if  $B_1 = X(G_1) \in \mathcal{B}$  with a corresponding condition for  $\sigma(Y)$ . It follows that (10.51) holds for each  $G_1 \in \sigma(X)$ ,  $G_2 \in \sigma(Y)$  iff  $P(X \in B_1, Y \in B_2) = P(X \in B_1)P(Y \in B_2)$  for each  $B_1 = X(G_1)$ ,  $B_2 = Y(G_2)$ . The ‘only if’ of the theorem then follows directly from the definition of  $\sigma(X)$ . The ‘if’ follows, given (8.38), from the fact that every  $B_i \in \mathcal{B}$  has an inverse image in any subfield on which a r.v. is measurable. ■

The ‘only if’ in the first line of this proof is essential. Independence of the subfields always implies independence of  $X$  and  $Y$ , but the converse holds only for the infimal cases,  $\sigma(X)$  and  $\sigma(Y)$ .

**10.22 Theorem** Let  $Y$  be integrable and measurable on  $\mathcal{G}_1$ . Then  $E(Y|\mathcal{G}) = E(Y)$  a.s. for all  $\mathcal{G}$  independent of  $\mathcal{G}_1$ .

**Proof** Define the simple  $\mathcal{G}_1$ -measurable r.v.s  $Y_{(n)} = \sum_{i=1}^n \gamma_i 1_{G_{1i}}$  on a partition  $G_{11}, \dots, G_{1n}$  of  $\Omega$  where  $G_{1i} \in \mathcal{G}_1$ , each  $i$ , with  $Y_{(n)} \uparrow Y$  as in **3.28**. Then